

3. Get Pixel Position

```
from astro_pi import AstroPi  
  
ap = AstroPi()  
  
pixel_list = ap.get_pixels()
```

4. Clear all Pixels

```
from astro_pi import AstroPi  
from time import sleep  
  
ap = AstroPi()  
  
red = (255, 0, 0)  
  
ap.clear() # no arguments defaults to off  
sleep(1)  
ap.clear(red) # passing in an RGB tuple  
sleep(1)  
  
ap.clear(255, 255, 255) # passing in r, g and b  
values of a colour
```

5. Rotate the LEDs

```
from astro_pi import AstroPi  
  
ap = AstroPi()  
  
ap.set_rotation(180)
```

6. Flip the LED Horizontally

```
from astro_pi import AstroPi  
  
ap = AstroPi()  
ap.flip_h()
```

7. Flip the LED Vertically

```
from astro_pi import AstroPi  
  
ap = AstroPi()  
ap.flip_v()
```

17. Get Gyroscope Reading

```
from astro_pi import AstroPi  
  
ap = AstroPi()  
  
raw = ap.get_gyroscope_raw()  
  
print("x: {x}, y: {y}, z: {z}".format(**raw))
```

18. Get Acceleration

```
from astro_pi import AstroPi  
  
ap = AstroPi()  
  
raw = ap.get_accelerometer_raw()  
  
print("x: {x}, y: {y}, z: {z}".format(**raw))
```



FURTHER DETAILS

<https://github.com/astro-pi>

<http://astro-pi.org/hardware/>

<https://www.raspberrypi.org/>



code

cheat book

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Usage: Code reference for the Astro Pi. Import the Astro Pi module and instantiate an object:

Load LX Terminal-type `sudo idle`



1. Set LED Pixels to Create an Image

```
from astro_pi import AstroPi  
  
ap = AstroPi()  
  
X = [255, 0, 0] # Red  
O = [255, 255, 255] # White  
  
question_mark = [  
    0, 0, 0, X, X, 0, 0, 0,  
    0, 0, X, 0, 0, X, 0, 0,  
    0, 0, 0, 0, 0, X, 0, 0,  
    0, 0, 0, 0, X, 0, 0, 0,  
    0, 0, 0, X, 0, 0, 0, 0,  
    0, 0, 0, X, 0, 0, 0, 0,  
    0, 0, 0, 0, 0, 0, 0, 0,  
    0, 0, 0, 0, 0, 0, 0, 0,  
    0, 0, 0, 0, 0, 0, 0, 0,  
    ]  
  
ap.set_pixels(question_mark)
```

2. Load an Image

Loads an image file, converts it to RGB format and displays it on the LED matrix. The image must be 8 x 8 pixels in size.

```
from astro_pi import AstroPi  
  
ap = AstroPi()  
  
ap.load_image("space_invader.png")
```

8. Scroll a Message

Scrolls a text message from right to left across the LED matrix and at a specified speed, colour and background colour. (*scroll_speed*, *back_colour*)

```
from astro_pi import AstroPi  
ap = AstroPi()  
ap.show_message("One small step for Pi!", \  
text_colour=[255, 0, 0])
```

9. Show a Single Letter

Displays a single text character on the LED matrix.

```
import time  
from astro_pi import AstroPi  
  
ap = AstroPi()  
  
for i in reversed(range(0,10)):  
    ap.show_letter(str(i))  
    time.sleep(1)
```

10. Get the Humidity Reading

```
from astro_pi import AstroPi  
  
ap = AstroPi()  
humidity = ap.get_humidity()  
  
print("Humidity: %s %%rH" % humidity)
```

11. Get the Current Temperature

```
from astro_pi import AstroPi  
  
ap = AstroPi()  
temp = ap.get_temperature()  
  
print("Temperature: %s C" % temp)
```

12. Get the Current Pressure

```
from astro_pi import AstroPi  
ap = AstroPi()  
  
pressure = ap.get_pressure()  
  
print("Pressure: %s Millibars" % pressure)
```

13. Get Orientation in Radians

```
from astro_pi import AstroPi  
  
ap = AstroPi()  
  
orientation_rad = ap.get_orientation_radians()  
  
print("p: {pitch}, r: {roll}, y: \  
{yaw}".format(**orientation_rad))
```

14. Get Orientation in Degrees

```
from astro_pi import AstroPi  
  
ap = AstroPi()  
orientation = ap.get_orientation_degrees()  
  
print("p: {pitch}, r: {roll}, y: \  
{yaw}".format(**orientation))
```

15. Get Orientation

```
from astro_pi import AstroPi  
  
ap = AstroPi()  
  
orientation = ap.get_orientation()  
  
print("p: {pitch}, r: {roll}, y: \  
{yaw}".format(**orientation))
```

16. Get Compass Reading

```
from astro_pi import AstroPi  
  
ap = AstroPi()  
north = ap.get_compass()  
  
print("North: %s" % north)
```

Note:

Some of the above lines of code end with a \ this indicates that the code is written on one single line but has been edited to fit the publication.